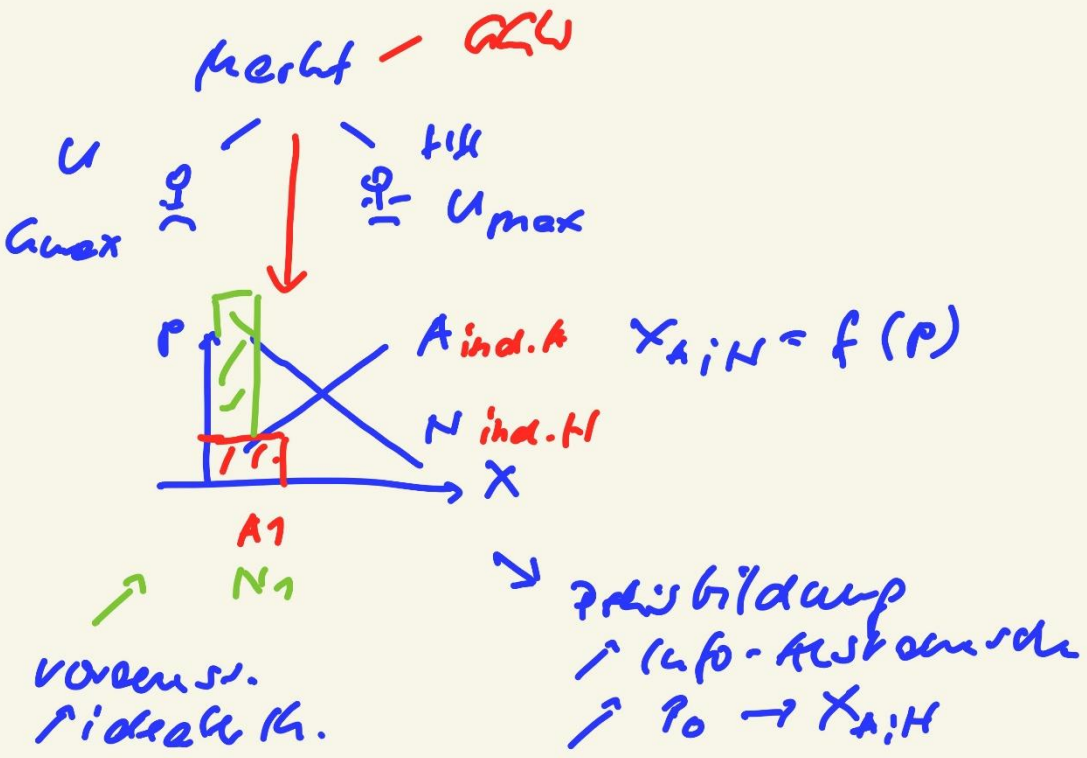
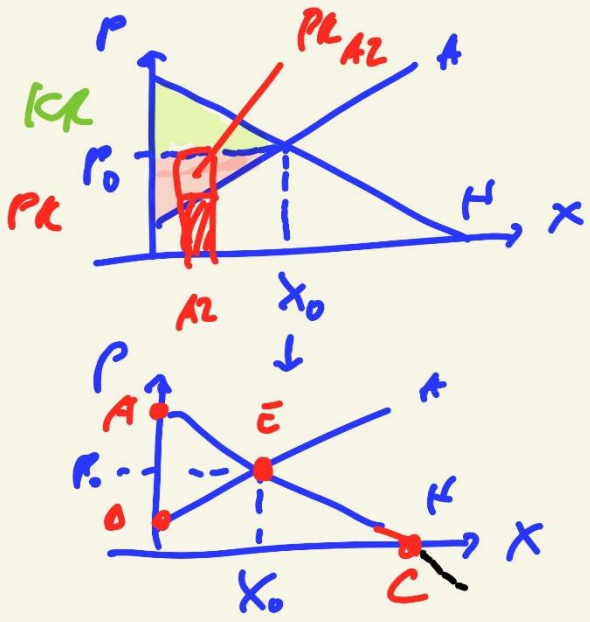




* → indiv. PR ↑
$(P_0 - PR_A) \cdot X_A$

$U = P_0 \cdot X_0$
$E[r_0; X_0]$
• A $X_0^N = 0$ *
• B
• C

Ziel:
PR ← G ↝ Dynamik

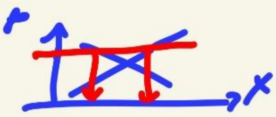
(1) P↓ X↑ PR↓
✓ ✓ (✓)

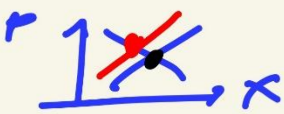
(2) X↑ K↓ Innovation

(3) neue Produkte
neue Preise
→ Allokation

Interventionen

inkonform | konform
MP | USt





PR
x↓

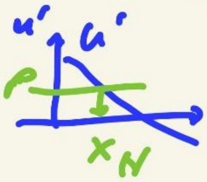
x_N x_A
$x_N < x_A$
↝ Folge-I

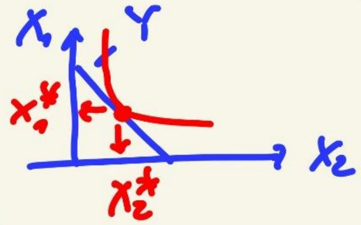
→ Staat
→ $\varepsilon_{x,p}$

ÜA 2

HH

x_N ?

1 Gut → U' → 

2 Güter 

$Y \to x_1; x_2$

Umax

U = const → IK

HHO

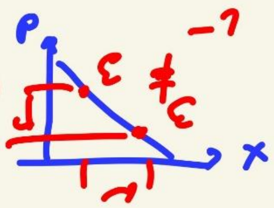
Hilfs-O

Y^{nom}

Y^{real}

P↓ P↑

$$\varepsilon_{x_N;P} = \frac{\Delta x / x_0}{\Delta P / P_0}$$



= −

0 … 1 … ∞

| |

$\Delta P \to 0$

$$= \frac{\Delta x}{\Delta P} \cdot \frac{P_0}{x_0}$$

$$= x' \cdot \frac{P_0}{x_0}$$

A-Analyse

X_A !

Gmax

- Prod.-fkt.

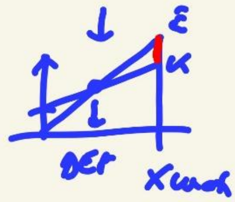
$O = f(I)$

$I = f(O)$

$k = \frac{K}{x}$

$K = f(x)$

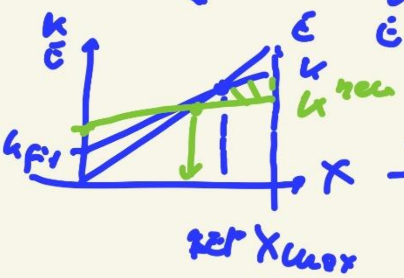
linear — Ertragsgesetz — CDPF Cobb-Douglas

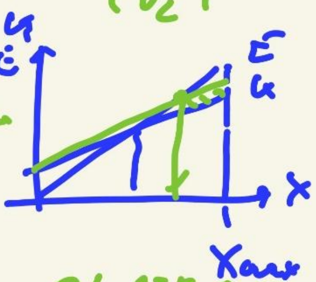


PA1 → Ratio

PA2 → Politik

CO_2 ↑





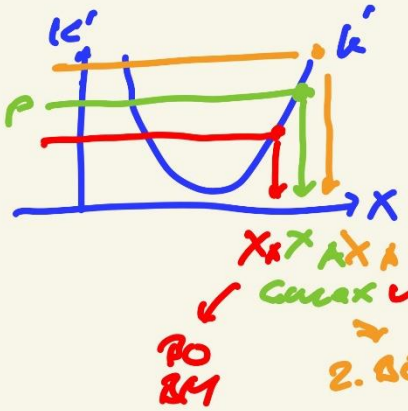
G↓ BEP↑

G↑ BEP↓

Gmax: $E' = K'$

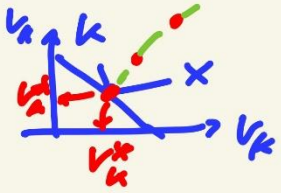
$E > K$

$E' = p$



COPF

$X = \alpha \cdot v_A^{\beta} \cdot v_K^{1-\beta}$



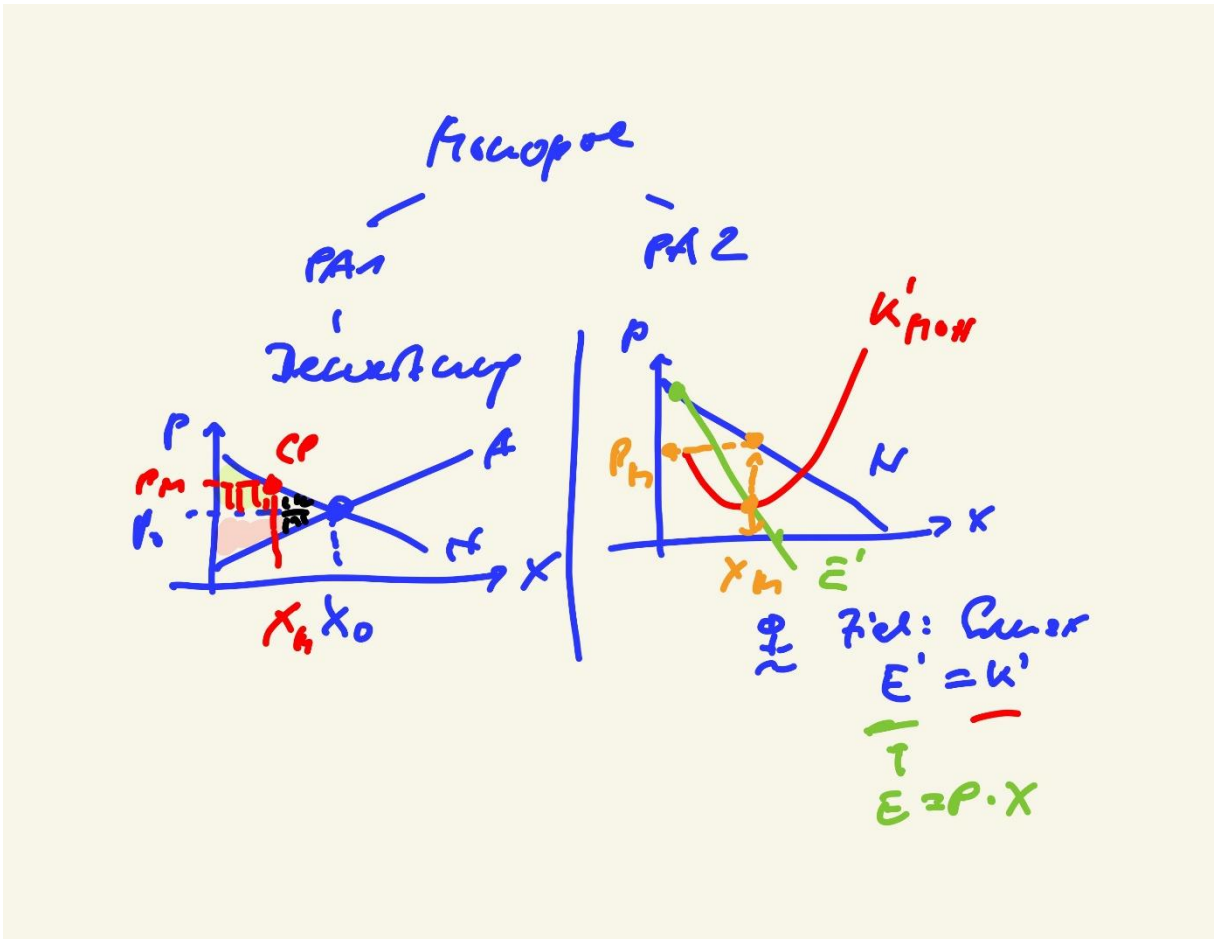
MKK $\Leftrightarrow$ $[v_A; v_K]$

$X = \text{const}$

K min

Exp.-Pfad =: MKK min $X = \text{const}$

tF → v_A^* ↑


Monopol
PA1
PA2
Preisdiskriminierung
p
CP
A
N
x
p_M
p_h
x_h
x_0
K'_{Mon}
E'
Ziel: Gewinn
$E' = K'$
$E = p \cdot x$